# Unitree Go2

## **New Creature of Embodied Al**

New and Improved Returning with Glory

Infinite Revolution



### Standard Ultra-wide 4D LIDAR Upgrades Recognition System by 200%

Go2 features with Unitree's self-developed 4D LIDAR L1 with 360° x90° hemispherical ultra-wide recognition, super small blind spot and a minimum detection distance as low as 0.05m, which makes Go2 realize all-terrain recognizing.



360°×90°

Ultra-wide Scanning

0.05m

Blind Spot

(Radar accuracy decreases at close range detection)

20m

@90% Reflectivity

Effective Frequency

21600 points/s 43200 points/s

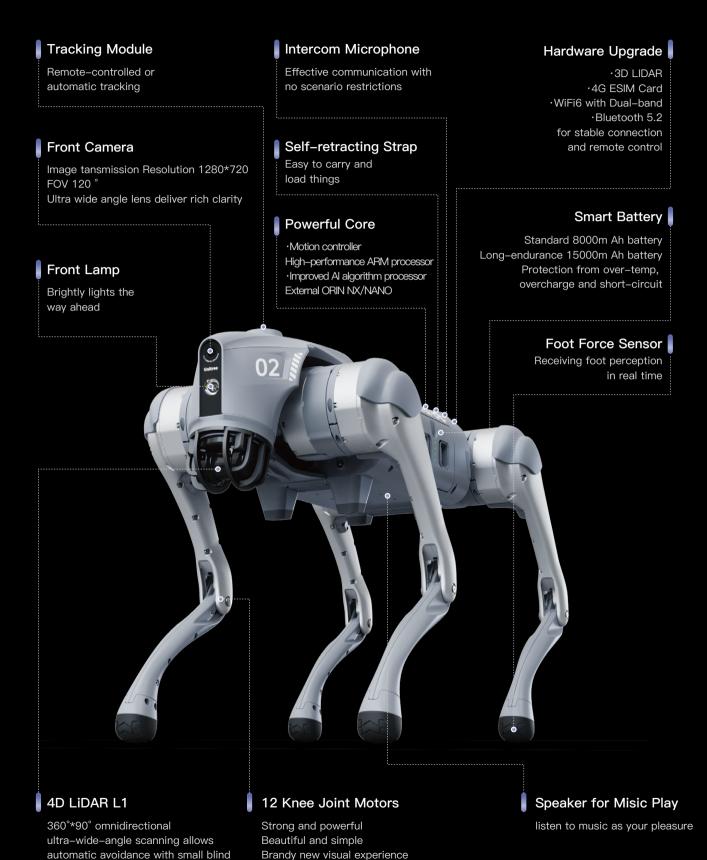
Frequency of Sample

100Klux

Anti-highlight Protection

### Your New Intelligent Friend

spot and stable operation



### New Intelligence—Unitree Go2



#### Intelligent Side-follow System 2.0

By adopting the new wireless vector positioning and control technology, the positioning accuracy is technically upgraded by 50%, the remote control distance is over  $30m_{[1]}$ , and combined with the optimised obstacle avoidance strategy, it can make the robot better traverse complex terrain.

[1] In open spaces with no shelter



# Motor performance enhanced by 30%

Go2 boasts a peak joint torque of 45N.m<sub>[2]</sub>, a new internal trace connecting technique, and heat pipe coolers to decrease temperature effectively.

[2] The maximum torque in the table refers to the maximum torque of the largest joint motor; the actual maximum torque varies for the 12 joint motors.



# Battery capacity and endurance upgraded by 150%

Go2 is equipped with a battery capacity increased to 8,000mAh, as a 15,000mAh ultra-long life battery is optional, and a voltage increased to 28.8V to improve motor efficiency, power and stability.



#### Various actions and poses

Go2 boasts a variety of poses such as jumping, stretching, shaking hands, cheering, pouncing, and sitting down.

### Intelligent Interaction

Have great fun with the APP



# Intelligent Avoidance Precise and Agile

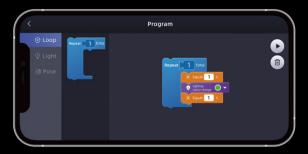
Equipped with 4D LiDAR L1, the robodog detects, captures and draws the 3D real world for user.



## Hd Picture Quality Real-time and Stable [1]

A new App realizes HD image transmission and real-time remote monitor. Built-in 4G and eSIM enables more stable connection and remote control.

[1]Transformation and quality varies considerably in different network environments.



## **Graphical Programming**Simple Yet Smarter

Optimise the graphical programming function, make it easy to complete the program design by simple drag, drop and connection. Make programming beginners easy to start and innovate.



#### **OTA Upgrades**

Keep Improving and Evolving to be Smarter

With user authorisation, the robot automatically connects to a cloud-based OTA service to upgrade its own programs to continuously improve the user experience.



### **Parameters**

Material	Mechanical &	Туре	AIR	PRO	EDU
Material					
Material					
Voltage					
Payload	Elec				
Payload	etro				
Page			~7kg (MAY ~ 10kg)		~8kg (MAY ~ 12kg)
Basic Computing Power	Pe	-			
Basic Computing Power	rfor				
Basic Computing Power	mar				
Peak Joint Torque (r)	90 1				
Range of motion					
Total   Intra-joint circuit (knee)					
Topic   Joint Heat Pipe Cooler	Joir		Body: -48~48°	Thigh: -200*~90* S	Shank: -156~-48°
Super-wide-angle 3D LIDAR	#	<u> </u>			•
HD Wide-angle Camera		Joint Heat Pipe Cooler	•	•	
HD Wide-angle Camera	For		•	•	•
Basic Action	ce S	Wireless Vector Positioning Tracking Module	0	•	•
Basic Action	èens	HD Wide-angle Camera	•	•	•
Auto-scaling strap	ğ	Foot-end force sensor	0	0	•
OTA upgrades		Basic Action	•	•	•
RTT2.0 Image transmission		Auto-scaling strap	0	•	0
Graphical programme		OTA upgrades	•	•	
Front lamp		RTT2.0 Image transmission	•	•	•
Bluetooth 5.2/4.2/2.1  4G  Voice Function [2]  ISS 2.0  Intelligent detection and avoidance  Charging Pile Compatibility  Secondary development [3]  Manual controller  High computing power modular  Smart battery  Endurance  About 1–2h  Bluetooth 5.2/4.2/2.1   Manual control [2]  Manual controller  Optional  Standard  About 2–4h	П	Graphical programme	•	•	•
Bluetooth 5.2/4.2/2.1  4G  Voice Function [2]  ISS 2.0  Intelligent detection and avoidance  Charging Pile Compatibility  Secondary development [3]  Manual controller  High computing power modular  Smart battery  Endurance  About 1–2h  Bluetooth 5.2/4.2/2.1   Manual control [2]  Manual controller  Optional  Standard  About 2–4h	eatı	Front lamp	•	•	•
AG	ıre L	WiFi6 with Dual-band	•	•	•
Voice Function 2   O	ist	Bluetooth 5.2/4.2/2.1	•	•	•
ISS 2.0		4G	0	•	•
Intelligent detection and avoidance Charging Pile Compatibility Secondary development [3]  Manual controller Optional Standard High computing power modular Smart battery Endurance Standard (8000mAh) Endurance  Ontional Standard Long endurance (15000mAh) About 2-4h		Voice Function [2]	0	•	•
Charging Pile Compatibility  Secondary development [3]  Manual controller  High computing power modular  Smart battery  Standard (8000mAh)  Endurance  Charging Pile Compatibility  Optional Standard  Optional Nvidia Jetson Orin  Standard (8000mAh)  Long endurance (15000mAh)  About 2–4h		ISS 2.0	0	•	•
Secondary development [3] O O Manual controller Optional Standard High computing power modular Optional Nvidia Jetson Orin Smart battery Standard (8000mAh) Long endurance (15000mAh) Endurance About 1–2h About 2–4h		Intelligent detection and avoidance	•	•	•
Manual controller Optional Standard  High computing power modular Optional Nvidia Jetson Orin  Smart battery Standard (8000mAh) Long endurance (15000mAh)  Endurance About 1–2h About 2–4h		Charging Pile Compatibility	0	0	•
High computing power modular  Smart battery  Standard (8000mAh)  Endurance  Optional Nvidia Jetson Orin  Standard (8000mAh)  Long endurance (15000mAh)  About 2–4h		Secondary development [3]	0	0	•
	Accessories	Manual controller	Optional		Standard
		High computing power modular	0		Optional Nvidia Jetson Orin
		Smart battery	Standard (8000mAh)		Long endurance (15000mAh)
		Endurance	About 1–2h		About 2–4h
, and a second s		Charger	Standard (33.6V 3.5A)		Fast charge (33.6V 9A)

 $<sup>\</sup>times$ The above parameters may vary in different scenarios and configurations, please subject to actual situations. If any change in the appearance of the product, please refer to the actual product.

<sup>[1]</sup> The maximum torque in the table refers to the maximum torque of the largest joint motor; the actual maximum torque varies for the 12 joint motors. [2] Voice functions include offline voice interaction, commands, intercom and music play. [3] For more information, please read the secondary development manual.

### **Extensions**

### LIDAR



Model	XT16
Size (Without Bracket)	Ф100.0 / 103.0 mm*76mm
Voltage Range	9-36V DC
Laser Wavelength	905mm
Fov	Horizontal 360°, Vertical 30° (–15°~+15°)

### LIDAR



Model	MID-360	
Size (without bracket)	65mm*65mm*60mm	
Voltage range	9-27V DC	
Laser wavelength	905mm	
FOV	Horizontal 360°, Vertical-7°~52°	

#### Depth Camera



Model	D435i
Size	124mm*29mm*26mm
Min Depth Distance	0.105m
Depth Image Resolution	1280*720 @ 30fps;
	848*480 @ 90 fps
Depth Field Of View	86° * 57° (±3°)

## High Computing Power Module



Model	Orin Nano 8GB、Orin NX 16GB
Voltage range	16-60V DC
Computing power	Nano supports up to 40 Tops
	NX supports up to 100 Tops
Expansion interface	USB3.0-Type A X1
	USB3.0-Type C X2
	Gigabit Ethernet port (standard RJ45) X2
	100Gb Ethernet (GH1.25-4PIN) X1
	M8 Air Plug Interface X1

#### Compact Servo Arm



Model	D1
Degree Of Freedom	6
Playload	About 500g
Max Armspan	550mm (without jaws)
Repeated Positioning Accuracy	About 0.2mm
Power Requirement	24V 2.5A (MAX 5A)
Interface	DC5.5-2.1
Motor Type	Servo
Power	60W
Control Interface	Control communication
	interface RJ45 (ETH)

## Remote Control with Screen 3 In 1



Number of cameras	2
Camera Resolution	1920x1080
Wireless frequency	2.4GHz
Searchlight Power	30W
Horn power	30W
Alarm light	Red and blue sharp-flash
Remote control with screen	MK15

# Unitree

Web: www.unitree.com Tel: +86 187 6713 8485 Email: laikago@unitree.cc







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