

## 7 Technical data

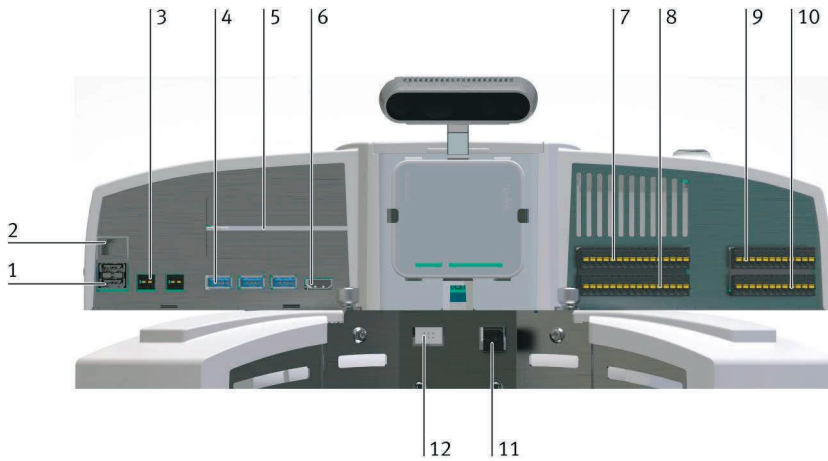
### 7.1 General data

Parameter	Value
Height	325 mm
Diameter	450 mm
Total weight (unladen weight)	20 kg
Total weight (including 4 rechargeable battery packs)	22.8 kg (approx. 700 g per rechargeable battery pack)
Payload	max. 30 kg (centered)
Degree of protection	IP 00
Battery voltage	18 V
Housing material	Stainless steel, PA6
Degrees of freedom	3 translational in x- and y-direction rotational about the z-axis
<b>Subject to change</b>	

### 7.2 Control and interfaces

Parameter	Value
Drive	
Wheels	3 x omnidirectional wheels with 120 mm diameter
Motors	3 x DC motors, maximum 3,600 rpm, with encoders and gear unit, gear ratio: 32:1
Controller	Embedded PC to COM Express specifications Intel i5, 8th generation, 2.5 GHz frequency, up to 4.2 GHz in turbo mode, 4 physical cores with hyperthreading Integrated UHD Graphics 630 Main memory: 8 GB RAM Hard disk: 64 GB SSD Operating system: Linux Ubuntu 18.04 LTS (64 bit) Motor control: microcontroller with 32-bit microprocessor and separate Ethernet interface
<b>Subject to change</b>	

### 7.2.1 Electrical connections



Parameter	Value	No. in fig.	Designation
Interfaces	2 x USB 2.0 (1 x occupied by Access point)	1	-XF2, -XF3
	1 x RJ-45 (occupied by Access point)	2	-XF1
	2 x 12 V WAGO-734-162 (max. 2 A total)	3	-XD5-1, -XD5-2
	4 x USB 3.0 (1 x occupied by camera)	4	-XF4, -XF5, -XF6, -XF9
	2 x PCI express slots (Gen3 4 x, extensions)	5	–
	1x HDMI	6	-XF7
	2 x Digital I/O connector	7, 8	-XD1, -XD2
	1 x analog input connector	9	-XD3
	1 x relay connector	10	-XD4
	1 x Wago 721-462 2-pole motor 4, power plug	11	–
	1 x MPE RM 2.54 2x3-pole motor 4, encoder	12	–
	WLAN to specification, 5 GHz and 2.4 GHz as client or access point in bridge mode	–	–
<b>Subject to change</b>			

Parameter	Value
Digital inputs/outputs	
Inputs: 8	Max. 24 V DC
Outputs: 8	Max. 2 A per output
	Max. 2 A total
Analog inputs	8
Relay toggle switch	2
Camera	USB 3.0 controlled stereo camera (Intel® RealSense™ depth camera D435) with two color cameras (1080p resolution) Infrared projector and RGB depth-sensing camera architecture with on-board processing
<b>Subject to change</b>	

### 7.2.2 Motor 4 encoder pin allocation

Pin	Function
1	GND 0 V
2	I (30-3)
3	W
4	V <sub>CC</sub> 5 V
5	B
6	n.c.
<b>Subject to change</b>	

### 7.2.3 Motor 4 power plug

Pin	Function
Left (view of plug)	+(PWM 0-24 V)
Right (view of plug)	GND (PWM)
<b>Subject to change</b>	

### 7.2.4 Access point specification

Parameter	Value
WLAN standards	5 GHz (IEEE802.11 ac/n/a) 2.4 GHz (IEEE802.11 b/g/n)
Transmission power	CE: max. 23 dBm (5 GHz) max. 20 dBm (2.4 GHz)
Interfaces	10/100 Mbps WAN/LAN port USB 2.0 port Micro USB port (power supply)
Power supply	5 V max. 2 A
<b>Subject to change</b>	